Architecture for Scalable, Self-*, human-centric, Intelligent, Secure, and Tactile next generation IOT

assist-iot

ASSIST-IoT: Next-generation IoT insights

Dr. Alejandro Fornés Leal

Polytechnic University of Valencia (UPV)



ASSIST-IoT Reference architecture



Reference NGIOT architecture (D3.7): Design principles, Views (functional, node, development, deployment, data), Verticals Additional considerations: Common endpoints (/metrics, /api, /version), monitoring and logging, encapsulation exceptions Considered: ISO/IEC/IEEE 42010, LSP programme architecture, the OpenFog consortium RA, and AIOTI HLA

ASSIST-IoT planes & verticals

41 enablers implemented (D4.3, D5.5)

- Following the design concepts and the guidelines of the Reference Architecture (only 3 exceptions)
- Covering several technological domains (AR, AI FL, Virtualization MANO, SDN, DLT, Cybersecurity, access control, Self-* mechanisms, etc.)
 Application and Services plane
- Different levels of design and development effort
- Many already public, others will be soon





ASSIST-IoT Orchestration

Key outcome: Smart orchestrator

- For IoT-Edge-Fog-Cloud ecosystems
- Compatible with K8s-based (v4, v3) and Openstack-based (v3) ecosystems
- Facilitates the lifecycle management of workloads, extended to environments with private and dynamic IP addresses
- Automated networking, policy rules and telemetry
- Policies for automating deployments **Insights:**
- Valid for many realistic NGIoT use cases, pending features for large, multi-domain ecosystems



ASSIST-IoT Enablers



ASSIST-IoT Enablers



ASSIST-IOT GWEN

- The ASSIST-IoT's Edge Node (GWEN) is the main hardware designed and manufactured by ASSIST-IoT:
 - It is a multipurpose gateway that can be adapted to several use cases, as it considers the most typical interfaces used in the industry (cellular – 5G, serial, WiFi, BLE, Ethernet, UWB)
 - It is based on open software, and jointly with the expansion modules, it can be fine-tuned to support any need at the edge (including AI and real-time capabilities)



ASSIST-IoT pilots

Enablers tested in highly **heterogeneous environments** to ensure minimization of the risk, involving **leading industries (D7.X)**



Port automation







Make provisions for predicting potentially dangerous situations in construction
 BS: <u>Occupational safety</u> (workers' health, geofencing, site control); <u>fall arrest detection</u>; <u>safe navigation</u> and healthy inspection with MR support



Cohesive vehicle monitoring and diagnostics



Increase monitoring capabilities in individual cars and at a fleet scale BS: Fleet in-service <u>emissions verification</u> and diagnostics; <u>exterior condition AI-based inspection</u> and documentation













b0_11 rdf:type om:Measure ; om:hasNumericalValue "255"^^xsd:integer ; om:Unit aiot_p2:tagAccelerationUnit .

b0_12 rdf:type om:Measure ; om:hasNumericalValue "256"^^xsd:integer ; om:Unit aiot_p2:tagAccelerationUnit .

:b0_13 rdf:type aiot_p2:AccelerationResult, sosa:Result ; aiot_p2:hasXValue _:b0_7 ; aiot_p2:hasYValue _:b0_9 ; aiot_p2:hasZValue _:b0_11 ; aiot_p2:accelerationWindow "l"^^xsd:positiveInteger .

b0_14 rdf:type aiot p2:AccelerationResult, sosa:Result ; aiot_p2:hasXValue _:b0_8 ; aiot_p2:hasYValue _:b0_10 ; aiot_p2:hasZValue _:b0_12 ; aiot_p2:accelerationWindow "2"^^xsd:positiveInteger .

ttps PrefixedName <u>u/pilot2 rdf/device/tag/36376</u>> rdf:type sosi schema:identifier "tag-36376"; sosa:hosts <<u>https://assist-iot.eu/pilot2_rdf/sensor/location</u>/

:b0_15 rdf:type sosa:Observation ;
 sosa:resultTime "2023-06-09T09:29:18.365239"^^xsd:dateTime ;
 sosa:hasResult _:b0_1, _:b0_13, _:b0_14, _:b0_5, _:b0_6 .

https://assist-iot.eu/pilot2_rdf/sensor/location/36376> rdf:typ sosa:madeObservation _:b0_15 .

https://assist-iot.eu/pilot2_rdf/worker/2> rdf:type aiot:User













ASSIST-IoT lessons learnt: now

- The design principles used are pillars of recently-started related initiatives
- The multi-cluster service mesh strategy applied has proved very useful to:
 - Ease the communication of different types of services, and along distributed environments
 - Secure the communication by using uTLS, and by allowing only exposed interfaces to communicate
- The primary packaging technology selected (Helm) is very flexible also for distributed ecosystems, still:
 - The values.yaml manifest, that modifies configuration parameters at deployment at all Helm charts, should be powerful and well-documented so that solutions can be truly effective
 - For more powerful, live configuration updates, the use of custom **operators** are one good practice
 - Other technologies with similar approaches could have been used, towards deployment flexibility
- However, there are **exceptions** in which virtualization is not possible or desired
 - Cybersecurity tools should be installed at host level to monitor possible threats
 - Some 5G functions, like UPF, show lower performance if deployed as containers
 - Some devices, like tiny edge devices, AR glasses etc., are not powerful enough to enable virtualization

ASSIST-IoT lessons learnt: next

- Edge native is still a field to further evolve. Basically, applications belonging to this category should leverage cloud-native principles while taking into account the unique characteristics of the edge in areas such as resource constraints, security, latency and autonomy
- The Cloud-Edge-IoT ecosystem is very heterogeneous and several implementations are available. Coordinated work is needed to work towards a common *taxonomy*, *glossary*, *and ontology of continuum orchestration*
- That heterogeneity prevents a one-solution-fits solution for the overall continuum. *Open platforms, marketplaces, reference implementations* for particular use cases are demanded
- Research, integrators, industry, EC... all the actors of the innovation chain must be aligned so the effort is actually transferred to the real world. Characterizing the real needs is key to translate the effort of the project outcomes into next actions, upscaling their TRL and influence standardization



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Thank You Questions?

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